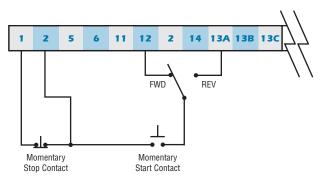
## SpinMaster™ Plus Terminal Strip

waster Plus Terminal Strip			
STOP	1		
CIRCUIT COMMON	2		
0-10 VDC SPEED REFERENCE INPUT			
10 VDC SUPPLY FOR SPEED POT			
12 VDC SUPPLY (50mA MAX.)			
START	12		
CIRCUIT COMMON	2		
OPEN COLLECTOR OUTPUT	14		
TB-13A FUNCTION SELECT	13A		
TB-13B FUNCTION SELECT	13B		
TB-13C FUNCTION SELECT	13C		
OPEN COLLECTOR OUTPUT	15		
4-20 ma speed reference input	25		
CIRCUIT COMMON	2		
0-10 OR 2-10 VDC OUTPUT: FREQ. OR LOAD			
0-10 OR 2-10 VDC OUTPUT: LOAD	30		
RS-485 SERIAL COMMUNICATIONS	TXA		
RS-485 SERIAL COMMUNICATIONS	ТХВ		

Shown below is a sample wiring diagram for a typical three-wire start/ stop control, using momentary contacts for start and stop commands, and a selector switch for direction.

Set Parameter 17 (Rotation) to Forward and Reverse (02). Set Parameter 10 (TB-13A) to Start Reverse (06).



### **Diagnostic and Display Messages**

DISPLAY	DESCRIPTION				
Speed Reference Codes					
СР	CONTROL PAD: The drive speed is controlled by the ▲ and ▼ buttons on the front of the drive.				
EI	EXTERNAL CURRENT: The drive speed is controlled by a 4-20 mA signal between TB-25 and TB-2.				
EU	EXTERNAL VOLTAGE: The drive speed is controlled by 0-10 VDC signal between TB-5 and TB-2.				
JG	JOG: The drive is in Jog mode and the speed is set by preset speed #2 (Parameter 32).				
OP	MOP: Contacts wired to TB-13B and 13C are used to increase and decreas the drive speed.				
Pr1-Pr7	<b>PRESET SPEEDS #1-7:</b> The drive speed is set by the selected Preset Speed (Parameters 31-37).				
Status Ir	ndication				
br	DC BRAKING: The DC braking circuit is activated.				
CL	CURRENT LIMIT: The output current has exceeded the CURRENT LIMIT setting (Parameter 25) and the drive is reducing the output frequency to reduce the output current. If the drive remains in CURRENT LIMIT for too long, it can trip into a CURRENT OVERLOAD fault (PF).				
Er	ERROR: Invalid data has been entered.				
GE	"GE" will be displayed if an attempt is made to change the OEM default settings when the drive is operating in the OEM mode (See Parameter 48).				
LC	FAULT LOCKOUT: Failed three restart attempts. Requires a manual reset.				
SE	SERIAL: The optional remote keypad is active as the user interface instead of the buttons on the front of the drive.				
SP	START PENDING: This is displayed during the 15 second interval between restart attempts.				
Diagnos	tic Codes				
AF	HIGH TEMPERATURE FAULT: Ambient temperature is too high.				
CF	CONTROL FAULT: A blank EPM, or EPM with corrupted data has been installed. Perform a factory reset (Parameter 48).				
cF	INCOMPATIBILITY FAULT: An EPM with a different parameter version has been installed.				
dF	DYNAMIC BRAKING FAULT: The drive has sensed the dynamic braking resistors are overheating.				
EF	<b>EXTERNAL FAULT:</b> TB-13A and/or TB13C is set as an external fault input and TB-13A and/or TB-13C is open with respect to TB-2.				
	· · · · · · · · · · · · · · · · · · ·				
GF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.				
GF HF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high; Deceleration rate is too fast; Overhauling load. Fast deceleration and				
	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high;				
HF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high; Deceleration rate is too fast; Overhauling load. Fast deceleration and overhauling loads may require dynamic braking.  SERIAL FAULT: The watchdog timer has timed out, indicating that the				
HF JF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high; Deceleration rate is too fast; Overhauling load. Fast deceleration and overhauling loads may require dynamic braking.  SERIAL FAULT: The watchdog timer has timed out, indicating that the serial link has been lost.  LOW DC BUS VOLTAGE FAULT: Line voltage is too low.  OUTPUT TRANSISTOR FAULT: Phase to phase or phase to ground short circuit on the output; Failed output transistor; Boost settings are too				
JF LF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high; Deceleration rate is too fast; Overhauling load. Fast deceleration and overhauling loads may require dynamic braking.  SERIAL FAULT: The watchdog timer has timed out, indicating that the serial link has been lost.  LOW DC BUS VOLTAGE FAULT: Line voltage is too low.  OUTPUT TRANSISTOR FAULT: Phase to phase or phase to ground				
JF LF OF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high; Deceleration rate is too fast; Overhauling load. Fast deceleration and overhauling loads may require dynamic braking.  SERIAL FAULT: The watchdog timer has timed out, indicating that the serial link has been lost.  LOW DC BUS VOLTAGE FAULT: Line voltage is too low.  OUTPUT TRANSISTOR FAULT: Phase to phase or phase to ground short circuit on the output; Failed output transistor; Boost settings are too high; Acceleration rate is too fast.  CURRENT OVERLOAD FAULT: VFD is undersized for the application;				
JF  LF  OF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high; Deceleration rate is too fast; Overhauling load. Fast deceleration and overhauling loads may require dynamic braking.  SERIAL FAULT: The watchdog timer has timed out, indicating that the serial link has been lost.  LOW DC BUS VOLTAGE FAULT: Line voltage is too low.  OUTPUT TRANSISTOR FAULT: Phase to phase or phase to ground short circuit on the output; Failed output transistor; Boost settings are too high; Acceleration rate is too fast.  CURRENT OVERLOAD FAULT: VFD is undersized for the application; Mechanical problem with the driven equipment.  SINGLE-PHASE FAULT: Single-phase input power has been applied to				
JF LF OF PF SF	DATA FAULT: User data and OEM defaults in the EPM are corrupted.  HIGH DC BUS VOLTAGE FAULT: Line voltage is too high; Deceleration rate is too fast; Overhauling load. Fast deceleration and overhauling loads may require dynamic braking.  SERIAL FAULT: The watchdog timer has timed out, indicating that the serial link has been lost.  LOW DC BUS VOLTAGE FAULT: Line voltage is too low.  OUTPUT TRANSISTOR FAULT: Phase to phase or phase to ground short circuit on the output; Failed output transistor; Boost settings are too high; Acceleration rate is too fast.  CURRENT OVERLOAD FAULT: VFD is undersized for the application; Mechanical problem with the driven equipment.  SINGLE-PHASE FAULT: Single-phase input power has been applied to a three-phase drive.  START FAULT: Start command was present when the drive was powered up. Must wait 2 seconds after power-up to apply Start command				

## **REGAL-BELOIT**

<u>Spin</u>Master plus™

# Variable Speed AC Motor Drives



## **Quick Reference Guide**

This Guide is intended as an aid to configure the SpinMaster™ Plus drive.

ACAUTION Before installing and operating the SpinMaster™ Plus drive, please read and become familiar with the SpinMaster™ Plus Installation and Operation Manual.



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## **Configuring the SpinMaster™ Plus Drive**

#### **Entering Program Mode:**

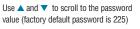
To access the parameters, press the **Mode** button. This will activate the password prompt. The display will read "00" and the right-hand decimal point will be blinking. Use the ▲ and ▼ buttons to scroll to the password value (the factory default password is 225) and press **Mode** to enter.

Press Mode

Display reads "00"



Upper right decimal point blinks



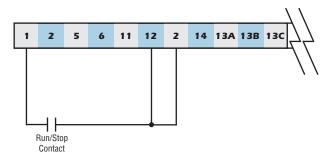


Press Mode to enter password

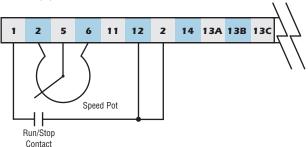
Once the **PROGRAM** mode is accessed, use the ▲ and ▼ buttons to scroll to the desired parameter number, and press the **Mode** button to see the parameter setting. Use the ▲ and ▼ buttons to change the parameter setting and press **Mode** to store the new setting.

#### **Connections:**

Below is a sample wiring diagram for two-wire start/stop control. The drive is ready to use right out of the box, with these simple control wiring connections; no parameter adjustments are required. Speed is controlled from the ▲ and ▼ buttons on the front of the drive.



To add a potentiometer for speed control, change Parameter #5 (Standard Speed Source) to 0-10 VDC (03).



### SpinMaster™ Plus Parameter Menu

NO.	PARAMETER NAME	RANGE OF ADJUSTMENT	FACTORY DEFAULT
01	Line Voltage	High (01), Low (02)	High (01)
02	Carrier Frequency	4 kHz (01), 6 kHz (02)	6 kHz (02)
02	Carrier Frequency	8 kHz (03), 10 kHz (04)	0 KI IZ (02)
		Normal (01), Start on Power-up (02),	
03		Start w/DC Brake (03)	
	Start Method	Auto Restart w/DC Brake (03), Flying	Normal (01)
		Restart 1 (05), Flying Restart 2 (06),	
		Flying Restart 3 (07)	
04	Stop Method	Coast (01), Coast with	Const (O1)
		DC Brake (02), Ramp (03),	Coast (01)
		Ramp with DC Brake (04)	
05	Speed Source	Keypad (01), Preset #1 (02),	Keypad (01)
		0-10 VDC (03), 4-20 mA (04) None (01), Run (02), Fault (03),	
06	TB-14 Output	Inverse Fault (04), Fault Lockout (05), At Set Speed (06)	None (01)
13	TB-14 Output	At Set Speed (06) Above Preset #3 (07)	None (01)
	15-15 Output	Current Limit (08), Auto Speed (09),	INOTIC (UT)
		Reverse (10)	
		None (01), 0-10 VDC Freg (02),	
08		2-10 VDC Freq (03),	
	TB-30 Analog Out	0-10 VDC Load (04),	None (01)
		2-10 VDC Load (05)	
	TB-31 Analog Out	None (01), 0-10 VDC Load (02),	
09		2-10 VDC Load (03),	None (01)
• /		Dynamic Braking (04)	, ,
		None (01), 0-10 VDC (02),	
		4-20 mA (03), Preset Speed #1 (04),	
		Run Reverse (05), Start Reverse (06),	
10	TB-13A Select	External Fault (07),	None (01)
		Remote Keypad (08), DB Fault (09),	
		Auxiliary Stop (10),	
		Accel/Decel #2 (11)	
		None (01), 0-10 VDC (02),	
11	TB-13B Select	4-20 mA (03), Preset Speed #2 (04),	None (01)
	15 135 Sciect	Decrease Freq (05), Jog Forward (06),	140110 (01)
		Jog Reverse (07), Auxiliary Stop (08)	
		None (01), 0-10 VDC (02),	
		4-20 mA (03), Preset Speed #3 (04),	
12	TB-13C Select	Increase Freq (05)	None (01)
		External Fault (06),	' '
		Remote Keypad (07), DB Fault (08),	
		Accel/Decel #2 (09)	
1.4	Control	Terminal Strip Only (01),	Terminal Str
14	Control	Remote Keypad Only (02)  Terminal Strip or Remote Keypad (03)	(01)
		Terminal Strip or Remote Keypad (03)  Disable (01),	
15		9600, 8, N, 2 with Timer (02),	
		9600, 8, N, 2 without Timer (03),	
	Serial Link	9600, 8, E, 1 with Timer (04),	9600, 8, N, 2
	SCHALLINK	9600, 8, E, 1 without Timer (05),	with Timer (0)
		9600, 8, 0, 1 with Timer (06),	
		9600, 8, 0, 1, without Timer (07)	
		3300, 0, 0, 1, Williout Hillor (07)	I

NO.	PARAMETER NAME	RANGE OF ADJUSTMENT	FACTORY DEFAULT
16	Units Editing	Tenths of Units (01), Whole Units (02)	Whole Units (02)
17	Rotation	Forward Only (01) Forward and Reverse (02)	Forward Only (01)
19	Acceleration Time	0.1 - 3600.0 sec	20.0 sec
20	Deceleration Time	0.1 - 3600.0 sec	20.0 sec
21	DC Brake Time	0.0 - 3600.0 sec	0.0 sec
22	DC Brake Voltage	0.0 - 30.0%	0.0%
23	Minimum Frequency	0.0 - Maximum Frequency	0.0 Hz
24	Maximum Frequency	Minimum Frequency - 240.0 Hz	60.0 Hz
25	Current Limit	30 - 180%	180%
26	Motor Overload	30 - 100%	100%
27	Base Frequency	25.0 - 500.0 Hz	60.0 Hz
28	Fixed Boost	0.0 - 30.0%	1.0%
29	Accel Boost	0.0 - 20.0%	0.0%
30	Slip Compensation	0.0 - 5.0%	0.0%
31-37	Preset Speeds	0.0 - Maximum Frequency	0.0 Hz
38	Skip Bandwith	0.0 - 10.0 Hz	0.0 Hz
39	Speed Scaling	0.0 - 6500.0	0.0
40	Frequency Scaling	3.0 - 2000.0 Hz	60.0 Hz
41	Load Scaling	10 - 200%	200%
42	Accel / Decel #2	0.1 - 3600.0 sec	20.0 sec
43	Serial Address	1 - 247	1
44	Password	000 - 999	225
47	Clear History	Maintain (01), Clear (02)	Maintain (01)
48	Program Selection	User Settings (01), 0EM Settings (02), Reset 0EM (03), Reset 60 (04), Reset 50 (05), Translate (06)	User Settings (01)
50	Fault History	View Only	(N/A)
51	Software Code	View Only	(N/A)
52	DC Bus Voltage	View Only	(N/A)
53	Motor Voltage	View Only	(N/A)
54	Load	View Only	(N/A)
55	0-10 VDC Input	View Only	(N/A)
56	4-20 mA Input	View Only	(N/A)
57	TB Strip Status	View Only	(N/A)
58	Keypad Status	View Only	(N/A)
59	TB-30 Output	View Only	(N/A)
60	TB-31 Output	View Only	(N/A)